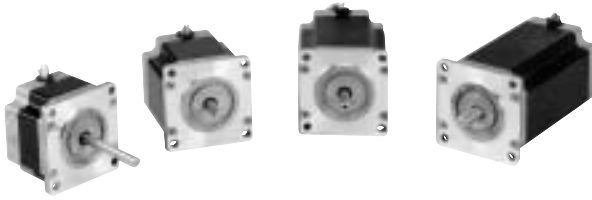


PACIFIC SCIENTIFIC T-SERIES NEMA 23 HIGH TORQUE MOTORS



Features

With holding torques to 380 oz-in, (356 lb-in), the T Series provide the highest torques per frame size in the industry—more than 3 and 5 phase designs.

Improved torque linearity (above rated current) provides high peak torque capability (duty cycle dependent, contact factory)

High torque at moderate speeds

Low detent torque harmonic

Rugged "housingless" square frame

Two phase design

Optional encoder mounting provisions

Optional terminal box construction

Wide selection of shaft configurations, terminations, and windings

Benefits

Optimized magnetics provide maximum performance in small envelope, reducing space required for the motor.

Acceleration boost to move loads even faster. Provides more torque for intermittent duty applications.

Cost effective alternative to servo motors

Provides smoother microstepping performance

Efficient use of volume for optimal magnetic circuit

Compatible with most drivers, smoother microstepping, and lower input power required vs. three phase for same torque

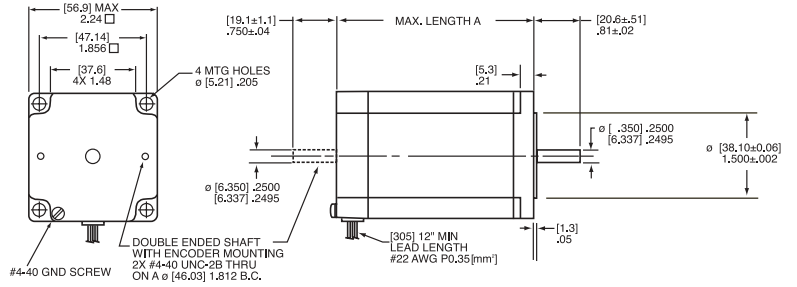
Optimizes control scheme

Enclosed connections for more demanding environments

Standard and custom configurations for cost effective system integration

LEADWIRE HOOKUP MODELS

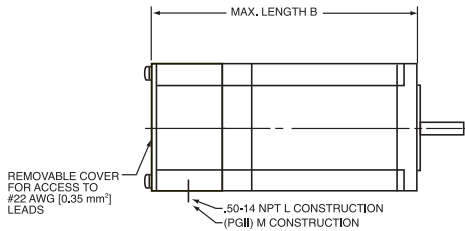
[mm] in



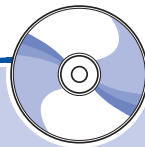
Leaded Motor Model	Max Length A	
	mm	in
T2H	41.6	1.64
T21	56.1	2.21
T22	77.7	3.06
T22	103.1	4.06

TERMINAL BOX CONSTRUCTION

[mm] in.



Leaded Motor Model	Max Length B	
	mm	in
T21	86.6	3.41
T22	108.2	4.26
T22	133.6	5.26



MOTIONEERING® CD-ROM

For more detailed product and selection information, see the MOTIONEERING CD-ROM inside the back cover of this catalog or visit our website at www.DanaherMotion.com.

PACIFIC SCIENTIFIC T-SERIES NEMA 23 HIGH TORQUE MOTORS

RATINGS AND CHARACTERISTICS SEE SYSTEM RECOMMENDATIONS AND DATA ON PAGES 88-89.

Typical Leadwire Motor Model Number	Connection ^①		Holding Torque ^② (2 phases on) oz-in (N-m) ±10%	Rated Current/Phase ^③ (amps DC)	Phase Resistance (ohms) ±10%	Phase Inductance ^④ (mH) Typical	Detent Torque oz-in (N-m)	Thermal Resistance ^⑤ (°C/watt)	Rotor Inertia oz-in-S ² (kgm ² x 10 ⁻³)	Net Weight kg (lbs)
	4 Lead	6 Lead								
T SERIES - 1/2 ROTOR STACK										
T2HNRHK-LNN-NS-00	●		74 (0.52)	5.3	0.19	0.63	2 (0.0141)	6.14	0.00154 (0.0114)	0.5 (1.03)
T2HNRHJ-LNN-NS-00	●		74 (0.52)	4	0.28	1				
T2HNRHL-LNN-NS-00	●		74 (0.52)	2.7	0.64	2.5				
T2HNRDL-LNN-NS-00	●		74 (0.52)	1.1	3.6	16				
T SERIES - 1 ROTOR STACK										
T21NRHK-LNN-NS-00	●		180 (1.27)	5.4	0.23	1.1	3 (0.0212)	4.64	0.0034 (0.0248)	0.7 (1.6)
T21NRHJ-LNN-NS-00	●		180 (1.27)	4.1	0.33	1.8				
T21NRHL-LNN-NS-00	●		180 (1.27)	2.7	0.85	4.6				
T21NRLE-LNN-NS-00	●		180 (1.27)	1.4	3.0	16				
T21NRDL-LNN-NS-00	●		180 (1.27)	1.1	4.9	30				
T SERIES - 2 ROTOR STACK										
T22NRHK-LNN-NS-00	●		280 (1.98)	6.6	0.20	0.85	6 (0.0424)	3.69	0.0056 (0.0408)	1.0 (2.3)
T22NRHJ-LNN-NS-00	●		280 (1.98)	4.1	0.49	2.5				
T22NRHL-LNN-NS-00	●		280 (1.98)	3.3	0.75	3.4				
T22NRGL-LNN-NS-00	●		280 (1.98)	2.5	1.3	7.1				
T22NRLE-LNN-NS-00	●		280 (1.98)	1.5	2.9	17				
T SERIES - 3 ROTOR STACK										
T23NRHK-LNF-NS-00	●		380 (2.68)	6.0	0.28	1.5	7 (0.0494)	3.04	0.0084 (0.0612)	1.5 (3.2)
T23NRHJ-LNF-NS-00	●		380 (2.68)	3.8	0.64	3.9				
T23NRHL-LNF-NS-00	●		380 (2.68)	3.0	1.0	6.2				
T23NRFL-LNF-NS-00	●		380 (2.68)	1.8	2.8	17				
T23NRLE-LNF-NS-00	●		380 (2.68)	1.5	4.1	24				

All ratings typical and at 25°C unless otherwise noted.

① Refer to Selection Guide for more information.

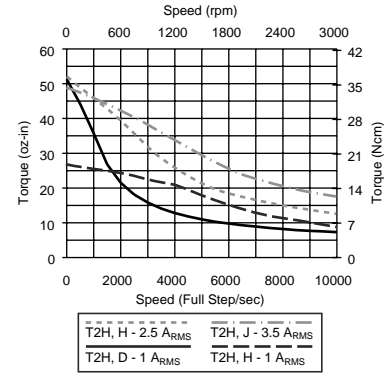
② With rated current applied.

③ Windings at 105°C and motor in still air at 40°C (without heat sink). Operation of these motors above rated current may cause demagnetization. Contact factory.

④ Small signal inductance as measured with impedance bridge at 1 kHz, 1 amp.

⑤ Thermal resistance measured with motor hanging in still air (unmounted).

The performance information shown in the torque/speed curves that follow show the T series of NEMA 23 step motors with windings, connections and current levels selected for maximum performance with the drives shown on this page. For additional assistance in sizing or selecting the stepper system appropriate for your application, contact Danaher Motion Customer Support at 815-226-2222.



SEE PAGE 74

- 24-40 VDC input
- Step/direction input or oscillator models
- Current selectable from 1 to 3.5 amps peak
- Microstepping - 4 step sizes

SEE PAGE 72

- 24-75 VDC input
- Step/direction input or oscillator models
- Current selectable from 0.625 to 7.1 amps peak
- Selectable step sizes, binary or decimal, full to 1/250 or 1/256

SEE PAGE 75

- 90-120 VAC input, 160 VDC bus
- Step/direction input
- Programmable inputs/outputs
- Current selectable from 0.75 to 4.0 amps
- Microstepping 200 to 100,000, selectable in increments of 200

SEE PAGE 76

- 90-120 VAC input, 160 VDC bus
- Step/direction input
- Current selectable from 0 to 7.9 amps
- 5,000 steps/rev to 50,000 steps/rev microstepping

SEE PAGE 77

- 90-120 VAC input, 160 VDC bus
- Programmable indexing
- Current selectable from 0 to 7.9 amps
- 36,000 steps/rev microstepping

PACIFIC SCIENTIFIC T-SERIES NEMA 23 STEPPER SYSTEMS

